

Last time:

$$G_{\alpha\beta} = K T_{\alpha\beta}$$

- Fixes only 6 degrees of freedom of metric, $g_{\alpha\beta}$
because $G^{\alpha\beta}_{;\beta} = 0$

Think of $g_{\alpha\beta}$ like A_α in EM

$G_{\alpha\beta}$ like $F_{\alpha\beta}$ in EM

EM: can always change $A_\alpha \rightarrow A_\alpha + \phi_\alpha$ w/out changing $F_{\alpha\beta}$
Maxwell's eqs. determine only some of A_α (up to gauge)

GR: can change $g_{\mu\nu} \rightarrow g_{\mu\nu}$ via coord xformation
w/out changing physics (comps of $G_{\alpha\beta}$ change too)

Einstein's Eqs determine $g_{\mu\nu}$ only up to coord xformations.

Example $T_{\alpha\beta} = 0$ flat space

$$ds^2 = -dt^2 + dx^2 + dy^2 + dz^2$$

or

$$ds^2 = -dt^2 + dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2$$

or

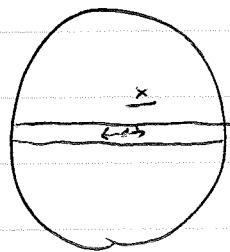
$$ds^2 = dv^2 - v^2 du^2 + dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2$$

all flat space

But unlike EM, where you can eliminate A_α , in GR you can't eliminate $g_{\mu\nu}$

The constant K

Bore a hole in the Earth, drop a particle inside.



Let it oscillate

Geodesic Deviation in LLF at center
of Earth, small oscillations:

$$\frac{d^2 x^i}{dt^2} = R_{00ij} \dot{x}^j$$

$$\text{or } \frac{d^2 x}{dt^2} = R^x_{00x} x$$

Newtonian physics:

$$\frac{d^2 x}{dt^2} = -\frac{G}{x^2} M(\text{inside sphere of radius } x)$$

$$= -\frac{G}{x^2} \left(\frac{4}{3} \pi x^3 g \right)$$

$$= -\frac{4\pi}{3} g x \quad (\text{let } G=1)$$

$$\text{Compare: } R^x_{00x} = -\frac{4\pi}{3} g = -R^x_{000}$$

$$\Rightarrow R^x_{000} = R_{00} = 4\pi g$$

$$\text{Compare with } G_{\alpha\beta} = kT_{\alpha\beta} = R_{\alpha\beta} - \frac{1}{2} g_{\alpha\beta} R$$

$$\text{Take trace: } R - 2R = kT = -R$$

$$\begin{aligned} \text{So } R_{00} &= KT_{00} - \frac{1}{2} g_{00} KT \\ &= K\left(T_{00} + \frac{1}{2}(T^0_0 + T^k_k)\right) \\ &= \frac{1}{2}KT_{00} + \frac{1}{2}KT^k_k \end{aligned}$$

Why? $\sim \frac{\text{speed of sound}}{(s)^2} \sim \frac{T_{00}}{T^k_k} \ll 1$

$$\text{So } R_{00} = \frac{1}{2}KT_{00} = \frac{1}{2}Ks$$

$$K = 8\pi$$

$$G_{\mu\nu} = 8\pi T_{\mu\nu}$$

Einstein's equations

Cosmological Constant

Einstein considered evolution of the universe.

- He assumed:
- Uniform density ρ
 - Homogeneous
 - Isotropic
 - Closed universe
 - Perfect fluid

\Rightarrow Restricts metric to $-dt^2 + a^2(t)[dx^2 + \sin^2 x(d\theta^2 + \sin^2 \theta d\phi^2)]$

3-sphere

$$G_{\alpha\beta} = 8\pi T_{\alpha\beta} \Rightarrow \left\{ \begin{array}{l} \left(\frac{da}{dt}\right)^2 + 1 = \frac{8}{3}\pi g a^2 \\ 2a \frac{d^2a}{dt^2} = -\left(\frac{da}{dt}\right)^2 - 1 - 8\pi p a^2 \end{array} \right.$$

$$\text{Also } T_{;\beta}^\alpha = 0 \Rightarrow \frac{d}{dt}(ga^3) = -P \frac{d}{dt}(a^3)$$

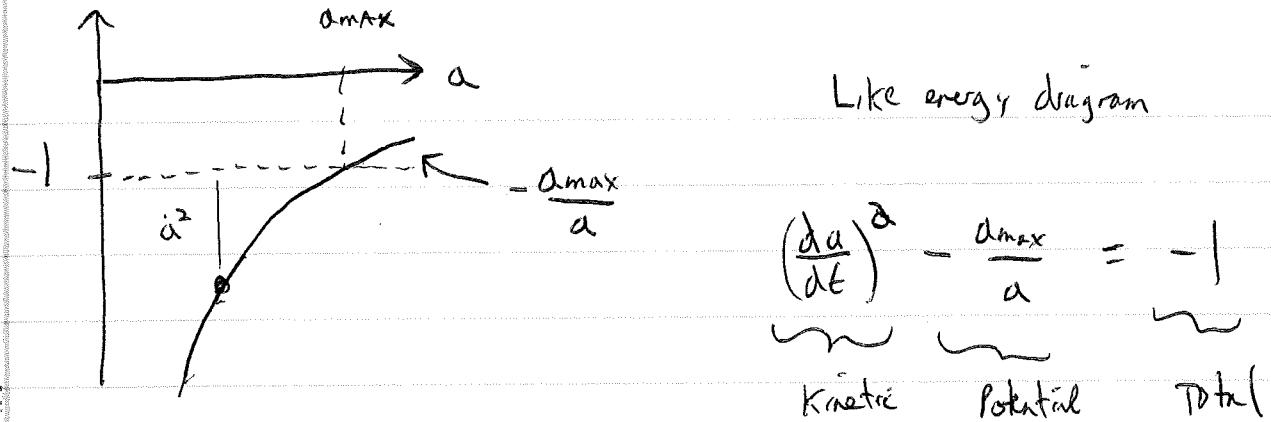
For present universe, $P \ll g$ ("matter-dominated")

$$\text{so } \frac{d}{dt}(ga^3) = 0 \quad \text{or } ga^3 = \text{const} = \frac{3}{8\pi} a_{\max}$$

$$\text{so } G_{\alpha\beta} = 8\pi T_{\alpha\beta} \Rightarrow$$

$$\left(\frac{da}{dt}\right)^2 - \frac{a_{\max}}{a} = -1$$

$$\frac{d^2a}{dt^2} = -\frac{a_{\max}}{2a^2}$$



\Rightarrow No static solution!

Universe expands to $a=a_{\max}$, then contracts.

What did Einstein do?

Give up "no curvature in empty space"

$$G_{ab} + \Lambda g_{ab} = 8\pi T_{ab}$$

cosmological constant.
Can get static
universe!

13 years later (1929) Hubble discovered universe is expanding.

Einstein's "Greatest Blunder".

Λ has 2 effects:

$$\text{- Effective density } \rho = \frac{\Lambda}{8\pi}$$

$$\left(\text{Think } T_{ab} = (\rho, p) \right)$$

Atkins

$$\text{- Effective negative pressure } P = -\frac{\Lambda}{8\pi}$$

Λ thought to be zero 1929 \approx 1998

Since ^{late} 1990s, observations show expansion of
Universe accelerating

Can be (so far) explained by $\Lambda \sim 1.3 \times 10^{-56} \text{ cm}^{-2}$
 $\sim 3 \times 10^{-46} M_{\odot}^{-2}$
"dark energy"

Λ is small No effect on lab experiments, black holes, ^{non cosmological} astrophysics.
only in low density large regions
(cosmology) does it matter.

$\sim 70\%$ of mass-energy in universe.

Lie Derivative

Def A

Suppose we have a vector field \vec{v}

Suppose we choose coordinates such that $\vec{v} = \frac{\partial}{\partial x^1}$

i.e. one of the coord basis vectors is \vec{v} .
 $\xrightarrow{\text{Lie derivative along } \vec{v}}$

Then in this coord system, define $\mathcal{L}_{\vec{v}} \tilde{T} = \frac{\partial T^{\alpha\beta...}}{\partial x^1} e_{\alpha} \otimes e_{\beta} \otimes ...$

$\xrightarrow{\text{Tensor Field}}$

$$\text{i.e. } (\mathcal{L}_{\vec{v}} \tilde{T})^{\alpha}_{\beta} = \frac{\partial}{\partial x^1} (T^{\alpha}_{\beta})$$

Def B

Scalar fields : define $\mathcal{L}_{\vec{v}} f = \vec{v} f$ directional deriv.

Vector fields : define $\mathcal{L}_{\vec{v}} \vec{u} = [\vec{v}, \vec{u}]$

Demand Leibnitz Rule, commutation w/ contraction, linearity

Show def A + B same for vectors:

$$\text{IF } \vec{v} = \frac{\partial}{\partial x^1} \text{ then } v^\alpha = \begin{cases} 1 & \alpha = 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\text{so } [\vec{v}, \vec{u}]^\beta = v^\alpha \frac{\partial u^\beta}{\partial x^\alpha} - u^\alpha \frac{\partial v^\beta}{\partial x^\alpha} \xrightarrow{\text{0 because } v^\alpha \text{ const}} \quad (\text{coord basis})$$

$$\delta^\alpha_i = \frac{\partial u^\alpha}{\partial x^i}$$

agrees with Def A.

Lie Derivative of 1-Form?

$$\mathcal{L}_{\tilde{v}} \langle \tilde{u}, \tilde{\omega} \rangle = \tilde{v} \langle \tilde{u}, \tilde{\omega} \rangle = V^e (\nabla_e u^\alpha) \omega_\alpha + V^e (\nabla_e \omega_\alpha) u^\alpha$$

①

$$\text{But also } \mathcal{L}_{\tilde{v}} \langle \tilde{u}, \tilde{\omega} \rangle = \langle \mathcal{L}_{\tilde{v}} \tilde{u}, \tilde{\omega} \rangle + \langle \tilde{u}, \mathcal{L}_{\tilde{v}} \tilde{\omega} \rangle$$

$$= \langle [\tilde{v}, \tilde{u}], \tilde{\omega} \rangle + \langle \tilde{u}, \mathcal{L}_{\tilde{v}} \tilde{\omega} \rangle$$

$$= (V^\alpha \nabla_\alpha u^\beta - u^\alpha \nabla_\alpha V^\beta) \omega_\beta$$

$$+ u^\alpha (\mathcal{L}_{\tilde{v}} \tilde{\omega})_\alpha$$

②

Compare ① + ②

$$u^\alpha (\mathcal{L}_{\tilde{v}} \tilde{\omega})_\alpha - u^\alpha (\nabla_\alpha V^\beta) \omega_\beta = V^e u^\alpha \nabla_e \omega_\alpha$$

must be true for all u^α

$$\Rightarrow \boxed{(\mathcal{L}_{\tilde{v}} \tilde{\omega})_\alpha = V^e \nabla_e \omega_\alpha + \omega_e \nabla_\alpha V^e}$$

In general,

$$(\mathcal{L}_{\tilde{v}} \tilde{T})_{\mu\nu\dots}^{\alpha\beta\dots} = V^\lambda T_{\mu\nu\dots}^{\alpha\beta\dots}$$

$$+ T_{\lambda\nu\dots}^{\alpha\beta\dots} V^\lambda_{;\mu} + \dots$$

$$- T_{\mu\nu\dots}^{\lambda\beta\dots} V^\alpha_{;\lambda} - \dots$$

Infinitesimal Coordinate Transformations

Let $X^\mu_{\text{new}}(P) = X^\mu_{\text{old}}(P) + \varepsilon V^\mu(P)$

\vec{V} = vector field

ε = small.

Then suppose you have a scalar Function f

$$\begin{aligned} \text{Then } f^{\text{new}}(X^\alpha_{\text{new}}(P)) &= f^{\text{old}}(X^\alpha_{\text{old}}(P)) && \text{scalars invariant at } P \\ &= f^{\text{old}}(X^\alpha_{\text{new}}(P) - \varepsilon V^\alpha(P)) && \text{if } \vec{V} = \frac{df}{dP} \\ &= f^{\text{old}}(X^\alpha_{\text{new}}(P)) - \varepsilon V^\alpha f_{,\alpha} \end{aligned}$$

↑ components
of

How about a tensor Field?

$$\begin{aligned} T^\alpha_\beta(X^\lambda_{\text{new}}(P)) &= \underbrace{\frac{\partial X^\alpha_{\text{old}}}{\partial X^\beta_{\text{new}}} \frac{\partial X^\lambda_{\text{new}}}{\partial X^\mu_{\text{old}}} T^\mu_\nu}_{\text{Transformation law}} T^\nu_\lambda(X^\lambda_{\text{old}}(P)) \\ &= (\delta^\nu_\beta - \varepsilon V^\nu_{,\beta})(\delta^\lambda_\mu + \varepsilon V^\lambda_{,\mu}) T^\mu_\nu(X^\lambda_{\text{old}}(P)) \varepsilon V^\lambda(P) \\ &= T^\alpha_\beta(X^\lambda_{\text{new}}(P)) - \varepsilon V^\nu_{,\beta} T^\alpha_\nu(X^\lambda_{\text{new}}(P)) \\ &\quad + \varepsilon V^\lambda_{,\mu} T^\mu_\alpha(X^\lambda_{\text{new}}(P)) \\ &\quad - \varepsilon T^\alpha_{,\lambda} V^\lambda \end{aligned}$$

Notice this is $T^\alpha_\beta(X^\lambda_{\text{new}}) = T^\alpha_\beta(X^\lambda_{\text{new}}) - (\mathcal{L}_{\vec{V}} \tilde{T})^\alpha_\beta(X^\lambda_{\text{new}})$

- Lie derivative $\mathcal{L}_{\vec{V}}(T)$ represents change in components of T under infinitesimal coord. transform.