

Stokes Theorem:

If $\tilde{\alpha}$ is an $n-1$ form

$$\overset{\text{Exterior deriv.}}{\int_{\text{volume}} d\tilde{\alpha}} = \int_{\text{boundary}} \tilde{\alpha}$$

n -form

Example. Given vector $\vec{V}$, can define 3-form (dual) $\tilde{\alpha} = \tilde{\tilde{E}}(\vec{V}, -, -, -)$

$$\text{or } \tilde{\alpha} = \frac{1}{3!} V^\alpha \epsilon_{\alpha\beta\gamma\delta} \tilde{dx}^\beta \wedge \tilde{dx}^\gamma \wedge \tilde{dx}^\delta = V^\alpha \underbrace{\tilde{\Sigma}_\alpha}_{\text{3-volume element}}$$

$$\text{Now compute } \tilde{d}\tilde{\alpha} = \frac{1}{3!} \partial_\epsilon [V^\alpha \epsilon_{\alpha\beta\gamma\delta}] \tilde{dx}^\epsilon \wedge \tilde{dx}^\beta \wedge \tilde{dx}^\gamma \wedge \tilde{dx}^\delta$$

But all 4-forms ^(in 4d) are proportional to $\tilde{\tilde{E}}$, so $\partial_\epsilon (V^\alpha \epsilon_{\alpha\beta\gamma\delta}) = q \epsilon_{\epsilon\beta\gamma\delta}$
for some q .

$$\text{Solve for } q: \quad \partial_\epsilon (\sqrt{-g} V^\alpha) \hat{\epsilon}_{\alpha\beta\gamma\delta} = q \sqrt{-g} \hat{\epsilon}_{\epsilon\beta\gamma\delta}$$

$$\text{contract w/ } \epsilon^{\epsilon\beta\gamma\delta}: \quad \frac{1}{\sqrt{-g}} \partial_\epsilon (\sqrt{-g} V^\alpha) \underbrace{\epsilon_{\alpha\beta\gamma\delta} \epsilon^{\epsilon\beta\gamma\delta}}_{-3! \delta_\alpha^\epsilon} = q \underbrace{\epsilon_{\epsilon\beta\gamma\delta} \epsilon^{\epsilon\beta\gamma\delta}}_{-4!}$$

$$\text{so } \frac{1}{\sqrt{-g}} \partial_\alpha (\sqrt{-g} V^\alpha) 3! = q 4! \quad \Rightarrow \quad q = \frac{1}{4} \frac{1}{\sqrt{-g}} \partial_\alpha (\sqrt{-g} V^\alpha)$$

$$\text{Therefore } \tilde{d}\tilde{\alpha} = \frac{1}{4!} \frac{1}{\sqrt{-g}} \partial_\epsilon (\sqrt{-g} V^\epsilon) \epsilon_{\alpha\beta\gamma\delta} \tilde{dx}^\alpha \wedge \tilde{dx}^\beta \wedge \tilde{dx}^\gamma \wedge \tilde{dx}^\delta$$

$$= \partial_\epsilon (\sqrt{-g} V^\epsilon) \tilde{dx}^0 \wedge \tilde{dx}^1 \wedge \tilde{dx}^2 \wedge \tilde{dx}^3$$

$$\text{so } \int \tilde{d}\tilde{\alpha} = \int \partial_\epsilon (\sqrt{-g} V^\epsilon) d^4x$$

So

$$\int_{\text{volume}} \partial_\mu (\sqrt{-g} V^\mu) d^4x = \int_{\text{boundary}} V^\alpha \Sigma_\alpha$$

3-volume element

$$= \int \frac{1}{3!} V^\alpha \epsilon_{\alpha\beta\gamma\delta} dx^\beta \wedge dx^\gamma \wedge dx^\delta$$

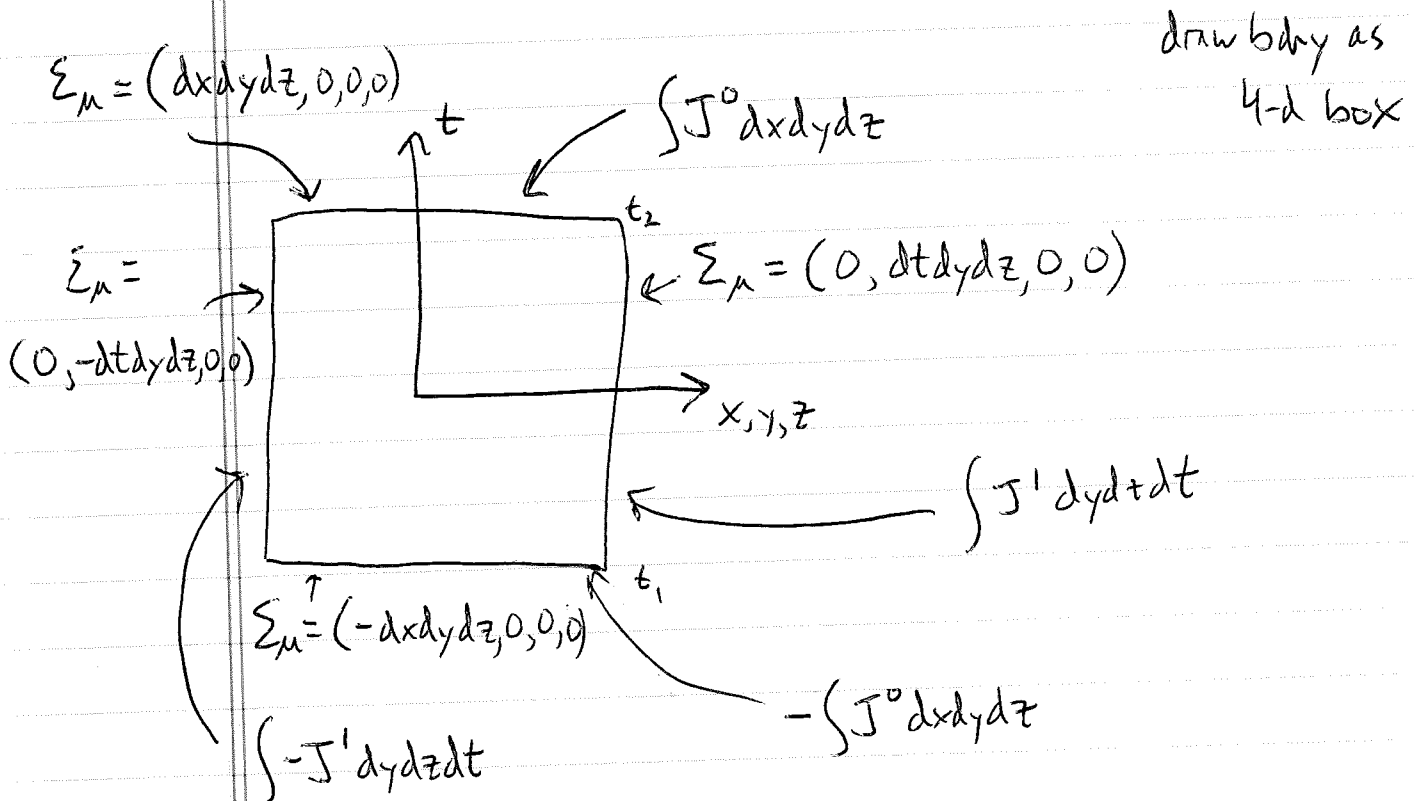
$$= \int V^\alpha n_\alpha \tilde{\Sigma}_{\text{surface}}$$

n_α = unit normal to surface

Example: Charge conservation in flat space

$$\partial_\mu J^\mu = 0$$

$$\int \partial_\mu J^\mu d^4x = 0 = \int_{\text{boundary}} J^\alpha \Sigma_\alpha$$



$$\int_{t_1} J^0 dx dy dz - \int_{t_2} J^0 dx dy dz + \int J^K \cdot n_K dA = 0$$

↑
Final charge

↑
initial charge

↑
Flux of
charge out of box

Sometimes one talks about ^{3d} volume 1-forms

$$\sum_{\alpha} = \star \tilde{\sum}_{\alpha}$$

Volume 1-form

dual

3D volume element (3-form)

Example
So if

$$\tilde{\sum}_{\alpha} = dx \wedge dy \wedge dz$$

$$\text{then } \sum_{\alpha} = dt$$

Same as unit normal 1-form

Stress-energy tensor $\tilde{T}$

Consider ^{distribution} of matter & fields

Define $\tilde{T}$ to be a 2nd-rank tensor, defined by:

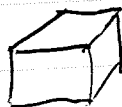
IF $\tilde{\Sigma}$ is a 3-d volume 1-form, then $\tilde{T}(-, \tilde{\Sigma}) = \vec{P}$

= 4-momentum that crosses from - side to + side of $\tilde{\Sigma}$

= (4-momentum in $\tilde{\Sigma}$ (if $\tilde{\Sigma}$ is timelike) or thru $\tilde{\Sigma}$ (otherwise))

Components:

Start with box ^{spatial}
Measure volume in its
own rest frame = V



$\vec{u}$ = 4-velocity of box

Volume 1-form $\tilde{\Sigma} = V \tilde{d}t$ ($= \star (V \tilde{d}x \wedge \tilde{d}y \wedge \tilde{d}z)$)

note, in rest frame of box, $u_0 = -1, u_i = 0$ so $\tilde{u} = -\tilde{d}t$

$$\text{so } \tilde{\Sigma} = -V \tilde{u}$$

tensor equation: true in all frames

$$\vec{P}_{\text{inside box}} = \tilde{T}(-, -V \tilde{u})$$

$$\text{or } p^\alpha = T^{\alpha\beta} u_\beta (-V)$$

$$\text{in rest frame } \frac{p^\alpha}{V} = T^{\alpha 0}$$

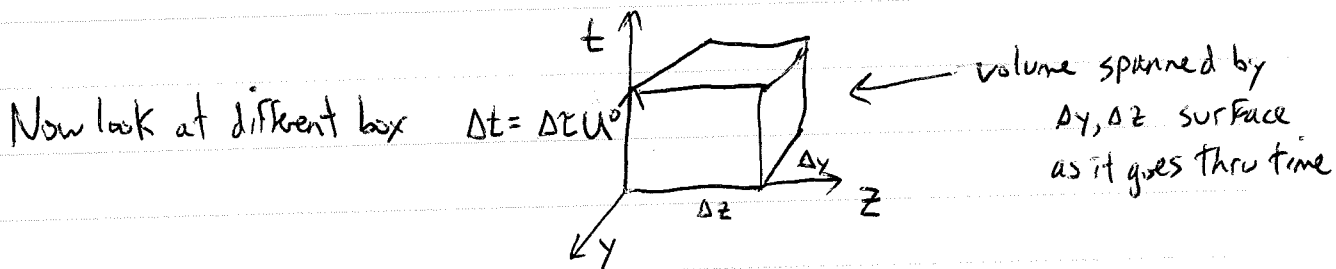
$$\Rightarrow \begin{aligned} T^{00} &= \text{energy dens} \\ T^{i0} &= i\text{-momentum density} \end{aligned}$$

or $E \overset{\text{energy in box}}{=} -\vec{P}_{\text{box}} \cdot \vec{U}$

$$= -P^\alpha U_\alpha$$

$$= V T^{\alpha\beta} U_\alpha U_\beta$$

$$= V T^{00} \text{ in rest frame}$$



Volume 1-form $\tilde{\Sigma} = A \Delta t \tilde{dx} = \star (A \Delta t \tilde{dt} \wedge \tilde{dy} \wedge \tilde{dz})$

↑
area of box $\Delta y \Delta z$
in rest frame

$$\text{so } \vec{P}_{\text{box}} = \tilde{T}(-, A \Delta t \tilde{dx})$$

$$\text{or } \frac{P^\alpha}{A \Delta t} = T^{\alpha\beta} (\tilde{dx})_\beta = T^{\alpha x}$$

$$\text{so } T^{0x} = \frac{\text{Energy}}{\text{Time} \cdot \text{Area}} \text{ crossing } \tilde{dx} = \text{energy Flux in } x \text{ direction}$$

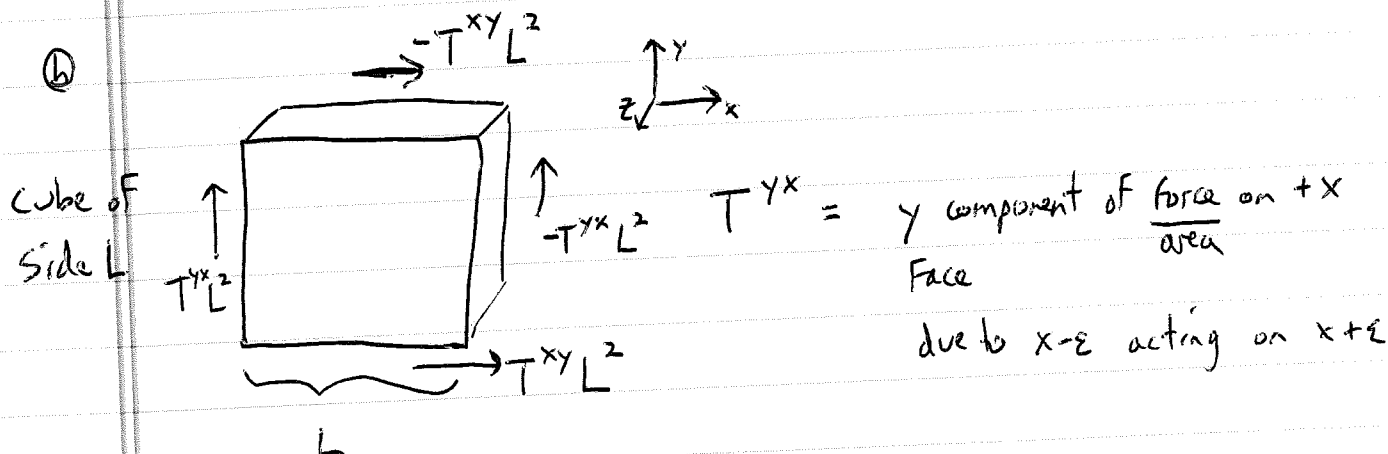
$$T^{ix} = i, x \text{ component of stress} = i\text{-component of momentum Flux in } x \text{ direction}$$

$$= i \text{ component of force per unit area in } x \text{ direction}$$

by matter at $x-\epsilon$ acting on matter at $x+\epsilon$

$\approx$ T is symmetric

- ① T^{0i} = energy flux in i direction
 = energy density $\cdot$ velocity ^{i}
 = mass density $\cdot$ velocity ^{i}
 = i -momentum density = T^{i0}



$T^{xy} =$ x component of $\frac{\text{force}}{\text{area}}$ on $+y$ Face

So torque in z -direction about center of box

$$\tau^z = (-T^{yx} L^2) \frac{L}{2} - (-T^{xy} L^2) \frac{L}{2} + (T^{yx} L^2) \left(-\frac{L}{2}\right) - (T^{xy} L^2) \left(\frac{L}{2}\right)$$

$$\tau^z = (T^{xy} - T^{yx}) L^3$$

Moment of inertia = $T^{00} L^3 \cdot L^2$

so $\text{ang. accel} = \frac{T^{xy} - T^{yx}}{T^{00} L^2}$
 $\rightarrow \infty$ as $L \rightarrow 0$ unless $T^{xy} = T^{yx}$

Example:

Cloud of particles, mass m , all with 4-velocity $\vec{u}$.

let $n = \frac{\text{\# of particles}}{\text{Volume}}$ in rest frame of particles scalar

In rest frame of particles $T^{00} = mn$

$$T^{\alpha\beta} = 0 \quad \alpha \neq 0 \text{ or } \beta \neq 0$$

Can write $T^{\alpha\beta} = mn u^\alpha u^\beta$

Example 2:

Perfect Fluid: described by 2 quantities

ρ = energy density in rest frame
 p = pressure in rest frame $\rangle$ scalars

Assume no heat transfer, no anisotropy, no viscosity, no shear stress.

Then in rest frame $\tilde{T} = \begin{pmatrix} \rho & p & 0 \\ 0 & p & p \end{pmatrix}$

let $\vec{u}$ = 4-velocity of fluid

In rest frame $T^{\alpha\beta} = \rho u^\alpha u^\beta + p(\eta^{\alpha\beta} + u^\alpha u^\beta)$

$\Rightarrow$ Tensor eqs. true in all frames