Supplement – Examples for Lecture V

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I. A WORKED EXAMPLE: VECTOR CALCULUS IN POLAR COORDINATES

In this section, we will do some examples from vector calculus in polar coordinates on \mathbb{R}^2 . This is a simple case, but should be useful to exercise the machinery. Recall that the metric tensor components were

$$g_{rr} = 1$$
, $g_{\theta\theta} = r^2$, and $g_{r\theta} = g_{\theta r} = 0$, (1)

and the inverse metric is

$$g^{rr} = 1$$
, $g^{\theta\theta} = \frac{1}{r^2}$, and $g^{r\theta} = g^{\theta r} = 0$. (2)

The coordinate basis vectors e_r and e_θ are not orthonormal, but we may define an orthonormal basis via

$$\mathbf{e}_{\hat{r}} = \mathbf{e}_r \quad \text{and} \quad \mathbf{e}_{\hat{\theta}} = \frac{1}{r} \mathbf{e}_{\theta}.$$
 (3)

A. Christoffel symbols

We begin by computing the Christoffel symbols for polar coordinates. The only nonzero derivative of a covariant metric component is

$$g_{\theta\theta,r} = 2r. \tag{4}$$

Now returning to the general rule,

$$\Gamma^{\epsilon}{}_{\delta\eta} = \frac{1}{2} g^{\epsilon\tau} (-g_{\delta\eta,\tau} + g_{\eta\tau,\delta} + g_{\delta\tau,\eta}), \tag{5}$$

we can directly read off the Christoffel symbols. They are:

$$\Gamma^{r}_{rr} = 0,$$

$$\Gamma^{r}_{\theta r} = \Gamma^{r}_{r\theta} = 0,$$

$$\Gamma^{r}_{\theta \theta} = \frac{1}{2}g^{rr}(-g_{\theta\theta,r}) = \frac{1}{2}(1)(-2r) = -r,$$

$$\Gamma^{\theta}_{rr} = 0,$$

$$\Gamma^{\theta}_{r\theta} = \Gamma^{\theta}_{\theta r} = \frac{1}{2}g^{\theta\theta}(g_{\theta\theta,r}) = \frac{1}{2}(r^{-2})(2r) = \frac{1}{r}, \text{ and}$$

$$\Gamma^{\theta}_{\theta\theta} = 0.$$
(6)

So of the 6 Christoffel symbols, only 2 are nonzero. This is typical of highly symmetrical manifolds (expressed in coordinates that use the symmetry).

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B. Covariant derivative of a vector field

Let's now find the covariant derivative of a vector field v. Using the rule from the last section,

$$v^{\alpha}_{;\beta} = v^{\alpha}_{,\beta} + \Gamma^{\alpha}_{\beta\gamma}v^{\gamma}. \tag{7}$$

Component by component, this reads

$$v^{r}_{;r} = v^{r}_{,r},$$

$$v^{r}_{;\theta} = v^{r}_{,\theta} - rv^{\theta},$$

$$v^{\theta}_{;r} = v^{\theta}_{,r} + \frac{1}{r}v^{\theta}, \text{ and}$$

$$v^{\theta}_{;\theta} = v^{\theta}_{,\theta} + \frac{1}{r}v^{r}.$$
(8)

The divergence of a vector field is

$$\nabla \cdot \boldsymbol{v} = v^r_{;r} + v^\theta_{;\theta} = v^r_{,r} + v^\theta_{,\theta} + \frac{1}{r}v^r.$$
(9)

C. Examples of vector fields and their properties

Consider the vector field v that points in the 1-direction of the original Cartesian coordinate system ($v = e_1$). It can be expressed in terms of its components in the orthonormal basis

$$v^{\hat{r}} = \cos \theta, \quad v^{\hat{\theta}} = -\sin \theta; \tag{10}$$

or in the coordinate basis,

$$v^r = \cos \theta, \quad v^\theta = -\frac{1}{r} \sin \theta.$$
 (11)

You know intuitively that this vector field is "constant," but that is not obvious in the polar coordinate system. We can still prove it, however, using Eq. (8):

$$v^{r}_{;r} = v^{r}_{,r} = 0,$$

$$v^{r}_{;\theta} = v^{r}_{,\theta} - rv^{\theta} = -\sin\theta - r(-\frac{1}{r}\sin\theta) = 0,$$

$$v^{\theta}_{;r} = v^{\theta}_{,r} + \frac{1}{r}v^{\theta} = \frac{1}{r}^{2}\sin\theta + \frac{1}{r}(-\frac{1}{r}\sin\theta) = 0, \text{ and}$$

$$v^{\theta}_{;\theta} = v^{\theta}_{,\theta} + \frac{1}{r}v^{r} = -\frac{1}{r}\cos\theta + \frac{1}{r}\cos\theta = 0.$$
(12)

As a less trivial example, we can search for an axisymmetric radial vector field \mathbf{E} ($E^{\theta} = 0$, E^{r} depends only on r and not θ) with zero divergence (except at the origin): $\nabla \cdot \mathbf{E} = 0$. Equation (9) tells us that we need

$$0 = E^{r}_{,r} + 0 + \frac{1}{r}E^{r}. (13)$$

Since s^r depends on r, we may then write

$$\frac{d}{dr}(rE^r) = rE^r_{,r} + E^r = 0. {14}$$

Therefore $E^{\hat{r}} = E^r \propto r^{-1}$. You may recognize this as the result that the electric field of a linear charge scales as 1/r.