Ph 236 – Homework 5

Due: Friday, November 11, 2011

1. Cosmological constant. [16 points]

Consider the highly symmetrical spacetime with line element given by

$$ds^{2} = \frac{1}{H^{2}\eta^{2}}(-d\eta^{2} + dx^{2} + dy^{2} + dz^{2}), \qquad (1)$$

where H > 0 is a constant, and in the domain $\eta < 0$. (This is known as *de Sitter spacetime*, and *H* is the Hubble constant.)

(a) Find the Einstein tensor for this spacetime.

(b) Prove that de Sitter spacetime is a vacuum solution of Einstein's equations in the presence of a positive cosmological constant for a particular choice of H. What is the relation between H and Λ ?

(c) Consider an observer whose world line is given by fixed spatial coordinates (x, y, z). Explain why this trajectory is a geodesic, and show that an infinite amount of proper time elapses before the observer reaches $\eta = 0$.

2. Magnetic part of the Weyl tensor and its interpretation. [20 points]

Consider the magnetic part of the Weyl tensor, defined in class in any local Lorentz frame:

$$\mathcal{B}_{\hat{i}\hat{j}} = \frac{1}{2} \epsilon_{\hat{j}\hat{k}\hat{l}} C_{\hat{i}\hat{0}\hat{k}\hat{l}}.$$
(2)

(a) Prove that $\mathcal{B}_{\hat{i}\hat{j}}$ is symmetric and has zero trace, $\mathcal{B}_{\hat{i}\hat{i}} = 0$.

Now let us consider the problem of gravitationally induced precession of a gyroscope. Consider a family of observers traveling on timelike geodesics, parameterized by the proper time τ and a parameter n denoting the choice of geodesic (this is similar to our setup in deriving the geodesic deviation formula). Suppose that the 4-velocity of neighboring observers is $\boldsymbol{v} = \partial \mathcal{P} / \partial \tau$ and the infinitesimal separation of neighboring curves is $\boldsymbol{\xi} = \partial \mathcal{P} / \partial n$. Suppose further that each observer carries a gyroscope whose angular momentum is pointed in the direction $\boldsymbol{\Omega}$. The gyroscopes are taken to be freely falling so $\boldsymbol{\Omega}$ is parallel-transported along each observer's trajectory – that is, $D\boldsymbol{\Omega} / \partial \tau = 0$.

(b) Prove that if $\boldsymbol{\Omega}$ is a purely spatial unit vector as seen by each observer at $\tau = 0$ – i.e. $|\boldsymbol{\Omega}(\tau = 0, n)|^2 = 1$ and $\boldsymbol{v} \cdot \boldsymbol{\Omega}(\tau = 0, n) = 0 \ \forall n$ – then at any subsequent time these equations remain true.

Now let us define the infinitesimal difference of direction in which neighboring gyroscopes point,

$$\boldsymbol{\Delta} = \frac{D\boldsymbol{\Omega}}{\partial n}.$$
(3)

(c) Prove that

$$\frac{D\Delta^{\alpha}}{\partial\tau} = R^{\alpha}{}_{\beta\gamma\delta}\Omega^{\beta}v^{\gamma}\xi^{\delta}.$$
(4)

[*Hint*: The proof of this uses methodology similar to that for the geodesic deviation equation that we used in Lecture Notes VII §IIIB.]

Now specialize to a local Lorentz frame, and assume we are located in vacuum so that $R_{\mu\nu} = 0$.

(e) Prove that

$$\frac{D\Delta^{\hat{i}}}{\partial\tau} = C_{\hat{i}\hat{j}\hat{0}\hat{k}}\Omega^{\hat{j}}\xi^{\hat{k}}.$$
(5)

(f) Express the relevant component of the Weyl tensor in terms of the magnetic part $\mathcal{B}_{\hat{i}\hat{j}}$ and show that

$$\frac{D\Delta^{i}}{\partial\tau} = \epsilon_{\hat{i}\hat{l}\hat{j}} \mathcal{B}_{\hat{l}\hat{k}} \xi^{\hat{k}} \Omega^{\hat{j}}.$$
(6)

This provides a physical interpretation of (and way to measure!) the magnetic part of the Weyl tensor: two sets of gyroscopes (inertial guidance systems) displaced by a separation ξ define reference frames that rotate relative to each other. The relative angular velocity of these reference frames is given by $\delta \omega_{\hat{l}} = \mathcal{B}_{\hat{l}\hat{k}}\xi^{\hat{k}}$.